

This lecture illustrates hash tables, using open addressing.

Before this lecture, students should have seen other forms of a Dictionary, where a collection of data is stored, and each data item has a key associated with it.


This lecture introduces hash tables, which are an array-based method for implementing a Dictionary. You should recall that we have seen dictionaries implemented in other ways, for example with a binary search tree. The abstract properties of a dictionary remain the same: We can insert items in the dictionary, and each item has a key associated with it. When we want to retrieve an item, we specify only the key, and the retrieval process finds the associated data.

What we do now is use an array to implement the dictionary. The array is an array of records. In this example, we could store up to 701 records in the array.


Each record in the array contains two parts. The first part is a number that we'll use for the key of the item. We could use something else for the keys, such as a string. But for a hash table, numbers make the most convenient keys.


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The numbers might be identification numbers of some sort, and the rest of the record contains information about a person. So the pattern that you see here is the same pattern that you've seen in other dictionaries: Each entry in the dictionary has a key (in this case an identifying number) and some associated data.


When a hash table is being used as a dictionary, some of the array locations are in use, and other spots are "empty", waiting for a new entry to come along.

Oftentimes, the empty spots are identified by a special key. For example, if all our identification numbers are positive, then we could use 0 as the Number that indicates an empty spot.

With this drawing, locations [0], [4], [6], and maybe some others would all have Number=0.


In order to insert a new entry, the key of the entry must somehow be converted to an index in the array. For our example, we must convert the key number into an index between 0 and 700 . The conversion process is called hashing and the index is called the hash value of the key.


There are many ways to create hash values. Here is a typical approach.
a. Take the key mod 701 (which could be anywhere from 0 to 700).

So, quick, what is $(580,625,685 \bmod 701) ?$


Three.


So, this new item will be placed at location [3] of the array.


The hash value is always used to find the location for the record.


Sometimes, two different records might end up with the same hash value.


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This is called a collision.

When a collision occurs, the insertion process will move forward through the array until an empty spot is found. Sometimes you will have a second collision...

...and a third collision...


But if there are any empty spots, eventually you will reach an empty spot, and the new item is inserted here.


The new record is always placed in the first available empty spot, after the hash value.


Time for another quiz . . . Did anyone end up with a hash value of 700 ?

Well, I did. My ID number is 155779023 , which has a hash value of 700 . (No, not really, but I needed to illustrate another kind of collision.

There is a collision with the last location of the array. In this case, you would circle back to the start of the array, and try location number 0 , then $1, \ldots$. until you find an empty spot. In this example, I would be inserted at location 0 , since that location is empty.


It is fairly easy to search for a particular item based on its key.


Start by computing the hash value, which is 2 in this case. Then check location 2. If location 2 has a different key than the one you are looking for, then move forward...


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Keep moving forward until you find the sought-after key...


In this case we find the key at location [5].


The data from location [5] can then be copied to to provide the result of the search function.

What happens if a search reaches an empty spot? In that case, it can halt and indicate that the key was not in the hash table.


Records can be deleted from a hash table...


But the spot of the deleted record cannot be left as an ordinary empty spot, since that would interfere with searches. (Remember that a search can stop when it reaches an empty spot.)

## Deleting a Record

a Records may also be deleted from a hash table.
$\square$ But the location must not be left as an ordinary "empty spot" since that could interfere with searches.
$\square$ The location must be marked in some special way so that a search can tell that the spot used to have something in it.


Instead we must somehow mark the location as "a location that used to have something here, but no longer does."

We might do this by using some other special value for the Number field of the record.

In any case, a search can not stop when it reaches "a location that used to have something here". A search can only stop when it reaches a true empty spot.


A quick summary . . .


To finish things off, I have hard copies of the next five slides. I tell the students that these are some records of my past students and I want to store them in a small hash table with size 5 (indexes 0 to 4). Of course, this is an unrealistic size, but it makes sure that they know the insertion, searching, and deletion algorithms. I then use five students from the front row to be the hash table locations. I insert the five items, remove Bill Clinton and do three searches (for Will Smith, Bill Clinton, and Elizabeth).






Feel free to send your ideas to:
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